

Manual

Classic P1

1 Quadrant Thyristor Drive

UNITEK

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G m b H

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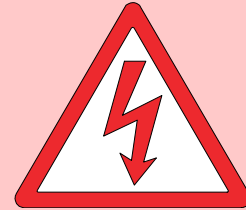
Contents	Page
1. Basic Information	
Safety advice	3
Standards and guidelines	3
General information	4
Features	5
Technical data	6, 7
2. Mechanical Installation	
Dimensions	9
3. Electrical Installation	
CE advice	10
Connection advice	11
Mains connection	12, 13
Motor connection	14
Field connection	15
Actual value connection	16
4. Adjustments	
Current control loop	17
5. Commissioning	19, 20
6. Guarantee	21
7. Protocol	22, 23
8. Drawings	
Connections	24
Circuit diagram P1 15A, 25A	25
Circuit diagram P1 40A	26

1 Basic Information

Electronic equipment is not fault proof. This fact should be borne in mind for all possible operating conditions.

ATTENTION - High Voltage

AC 250/440V~, DC 180/300V=



Before installation or commissioning begins, this manual must be thoroughly read and understood by the technical staff involved.
If any uncertainty arises, the manufacturer or dealer should be contacted.
P1 devices are power electric parts used for regulating energy flow.
Protection rating IP00.

Standards and guidelines

The device and its associated components can only be installed and switched on where the local regulations and technical standards have been strictly adhered to:

EU Guidelines	89/392/EWG, 84/528/EWG, 86/663/EWG, 72/23/EWG EN60204, EN50178, EN60439-1, EN60146, EN61800-3
IEC/UL	IEC364, IEC 664, UL508C, UL840
VDE Regulations	VDE100, VDE110, VDE160
TÜV Regulations	
Trade body guidelines	VGB4

The user must ensure that in the event of:

- device failure
 - incorrect operation
 - loss of regulation or control
- the axis will be safely de-activated.

It must also be ensured that the machine or equipment are fitted with device independent monitoring and safety features.

Setting adjustments

- should only be carried out by suitably trained personnel
- should only be carried out in accordance with health and safety guidelines

Assembly

- should only be carried out when all voltages have been removed.

QS

Test results are archived with the device serial number by the manufacturer.

CE

The device adheres to the following: Guideline EU 89/336/EWG. EMC standards EN61000-2 and EN61000-4.

Attention

This device description MANUAL P1 only describes the basic control unit and it must be read in conjunction with a control manual (e.g. REG).



The following control units for 1 quadrant control are available:
analogue control REGx

General information

In conjunction with a control board (e.g. REG) the Classic P1 range of thyristor drives act as current controllers (moment of inertia controllers). A 26-pin connector, common to all boards, is used to connect the power section and the control electronics. Using this interface it is possible for any external control arrangement including third party equipment to drive the power section.

Q2 drives are used to control the speed, the voltage or the moment of inertia of dc motors.

Build

- switch cabinet mounting
- according to the VDE, DIN and EU regulations
- standard control electronics REG
- intrinsically safe power section with current control loop
- optional units

Galvanic isolation between

- the power section and the housing
- the power section and the control electronics

The distance of air gaps and leakage paths adhere to the VDE standards (>8mm).

Components

- fully insulated thyristor modules, comfortably over-dimensioned
- only components customary in trade and industrially standardised are used
- LED displays
- DIP switches for the P-I adjustment of the current control loop
- precision potentiometers for fine adjustments
- plug-in jumpers for the system set-up

Characteristics

- * Series Classic P1
- * Thyristor drive for dc motors
- * Power range 2.7kW to 12kW
- * Drive in the first quadrant
- * Intrinsically safe power section
- * Fast analogue current control
- * 26-pin interface
- * Features of the control electronics:
see Manual REG or third-party product documentation
- * Optional units

P1 230/180-x

Power connection 200 ... 250V~
 Auxiliary voltage connection 200 ... 250V~
 Output voltage max. +180V=
 Cooling self

P1 230/180-		15	25	40
Input current	A~	16,5	27,5	44
Output current - peak - continuous	A= A=	30 15	50 25	80 40
El. power	kW	2.7	4.5	7.2
Input fuses (fast acting) input	A	20	30	50
Mains chokes	Typ mH	K78-16 1.2	K84-25 0.7	K84-50 0.5
Armature chokes	Typ mH	EI135A-16 33	EI135B-24 16	EI150B-35 8
Dimensions w x h x d	mm	200x160x112	200x160x120	200x160x120

P1 400/300-x

Power connection 360 ... 440V~
 Auxiliary voltage connection 360 ... 440V~
 Output connection max. +300V=
 Cooling self

Gerät P1 400/300-		15	25	40
Input current	A~	16.5	27.5	44
Output current - peak - continuous	A= A=	30 15	50 25	80 40
El. power	kW	4.5	7.5	12
Input fuses (fast acting) Input	A	20	30	50
Mains chokes	Typ mH	K78-16 1.2	K84-25 0.7	K84-50 0.5
Armature chokes	Typ mH	EI135A-16 33	EI135B-24 16	EI150B-35 8
Dimensions w x h x d	mm	200x160x112	200x160x120	200x160x120

1 Basic Information

Specification	
Mains frequency	50 or 60 Hz $\pm 5\%$
Protection rating	IP 00
Format	VDE 0100 groupe C, VDE 0160
Humidity rating	class F acc. to DIN 40040
Site of installation	< 1000m above sea level
Operating temperature range	0 ... 45°C
Extended operating temp. range	up to 60° C reduced 2%/ °C
Storage temperature range	-30° C to + 80° C
Amplification - input signal - output	0 ... + 10 Volt= 0 ... + 200% type current
Enable	+10 Volt
Current control loop circuitt - control precision - control range	$\pm 2\%$ >1: 50
Speed control loop circuit with REG - control precision (without actual value error) control range	$\pm 0,1\%$ >1: 200

Interface control electronics X3

Function

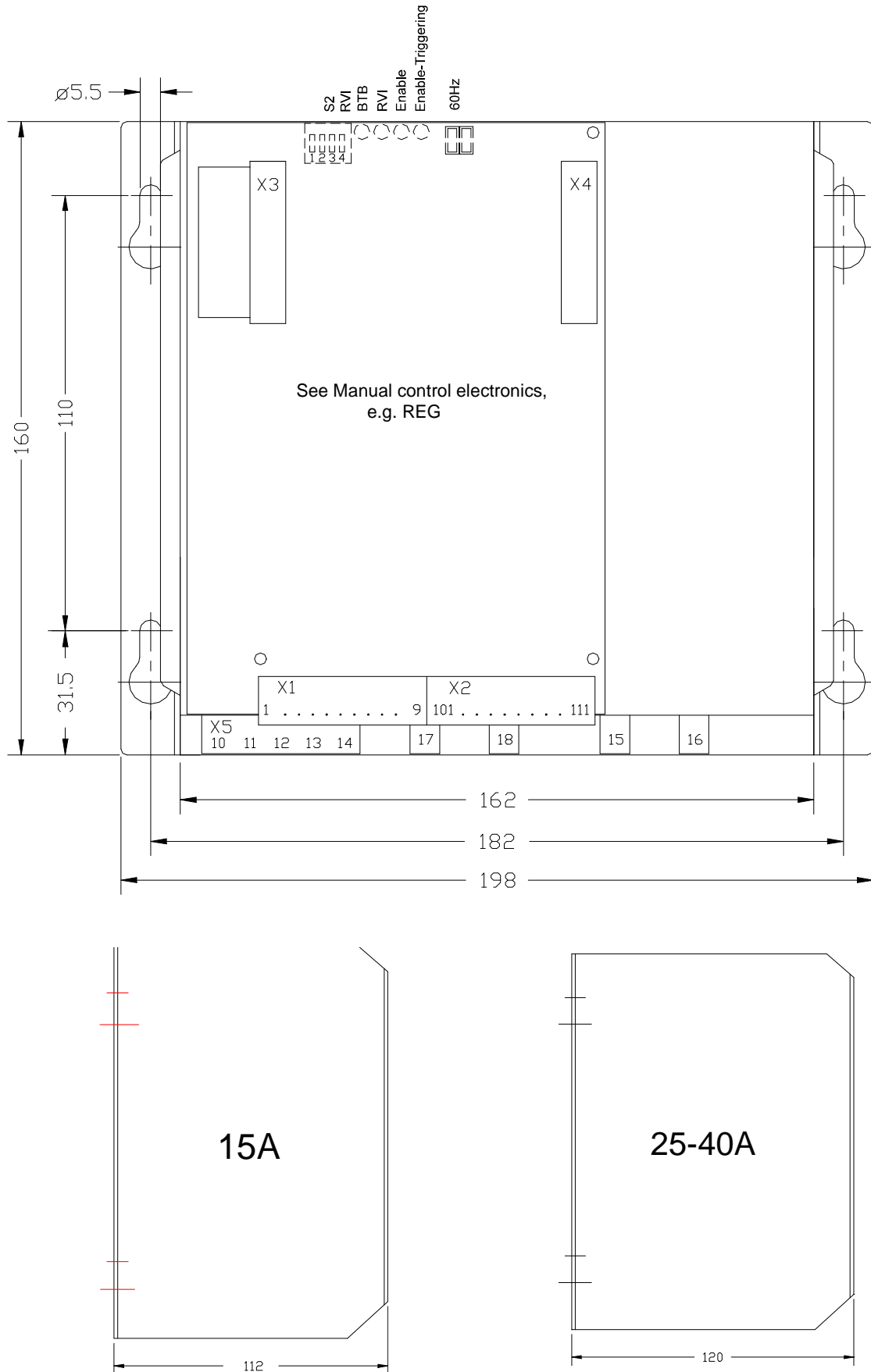
Connector no.

+ 24V	$\pm 10\%$	X3: 1 and 2
+ 15V	$\pm 2\%$	X3: 3 and 4
- 24V	$\pm 10\%$	X3: 5 and 6
- 15V	$\pm 2\%$	X3: 7 and 8
Device GND	0	X3: 9, 10, 11, 12, 13, 14
I command value (GND)	0	X3: 15
I command value (signal)	+10V=	X3: 16
Current controller enable	+10V=	X3: 17
Drive disable1	+10V=	X3: 18
Drive disable 2	+10V=	X3: 19
N (speed) actual	+5V=	X3: 20
I (current) actual	+5V=	X3: 21
Over-current power section	n/a	X3: 22
Trigger angle1	+10V=	X3: 23
Trigger angle 2	+10V=	X3: 24
Drive ready BTB	+10V=	X3: 25
not assigned	n/a	X3: 26



2 Mechanical Installation

Top view Classic P1 x/x dimensions



CE Advice

The devices adhere to the EU guidelines 89/336/EWG and the technical standards EN 61000-2 and 61000-4 provided that the following conditions are observed:

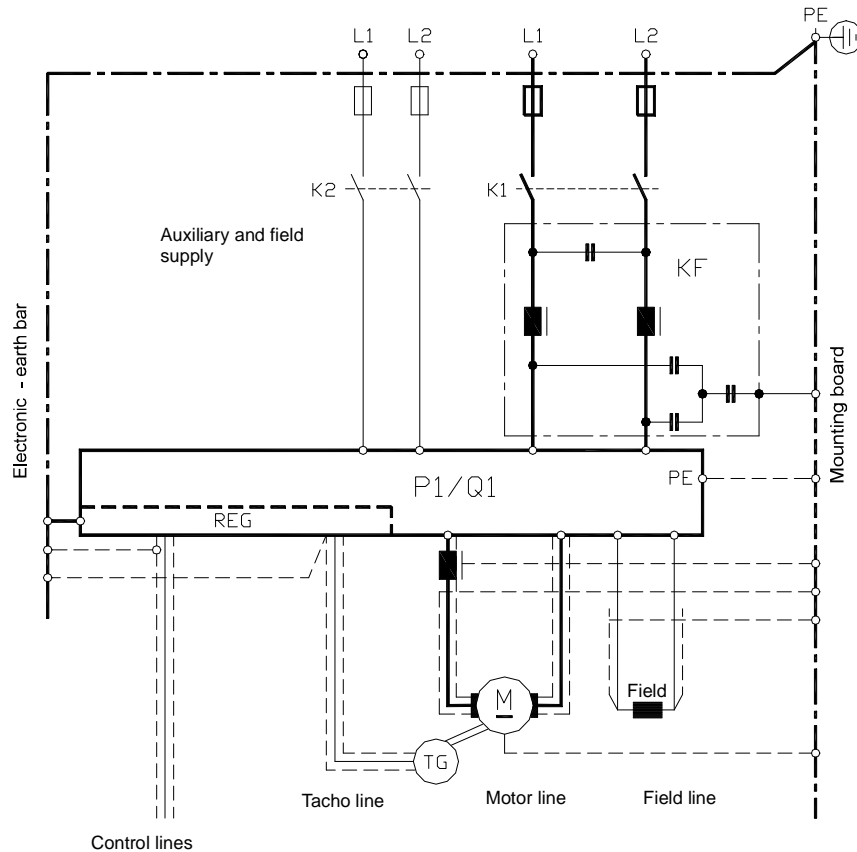
- The device, the power choke, and the filter capacitors are mounted on a 500x500x2 mm mounting plate.
- The mounting plate must be connected to ground using a 10mm² wire.
- The motor housing must be connected to ground using a 10mm² wire.
- The device ground X1:8 must be connected to the mounting plate using a 2.5mm² wire.
- Device PE screw must be connected to the mounting plate using a 4mm² wire, l = 50mm.

Connection:

Power choke type:	see technical details
Filter capacitors:	0.5µF/600V~ 2 x 1µF (x) + 1 x 0.5µF (y)
Conductor length between the device and the power choke	<250mm

Motor connection:

Motor conductors	l = 1.5m, shielded
Tacho and all control lines	l = 1.5m, shielded
Shielding connected to PE	



KF= Commutation choke with filter capacitor

3 Electrical Installation

Attention:

The order of the connections to the connector numbers or screw terminals is obligatory. All further advice is non-obligatory.

The input and output conductors may be altered or supplemented in accordance with the electrical standards.

Note:

- Connection and operating instructions
- Local regulations
- EU guideline 89/392/EWG, 84/528/EWG, 86/663/EWG
- VDE and TÜV regulations and Trade body guidelines
- CE advice, EMC



Connection				
Conductor minimal cross - section				
Type current	A	15	25	40
ac power supply	mm ²	1.0	2.5	4
Motor line	mm ²	1.0	2.5	4
Auxiliary voltage	mm ²	0.5	0.5	0.5

Connection advice

This connection advice is a general information and non-obligatory.

Note:

- **Connection and operating instructions**
- **Local regulations**
- **EU guideline 89/392/EWG**
- **VDE and TÜV regulations and Trade body guidelines**



Switch on the auxiliary voltage and the supply voltage simultaneously.

Switch off the supply voltage after the auxiliary voltage

Input filter

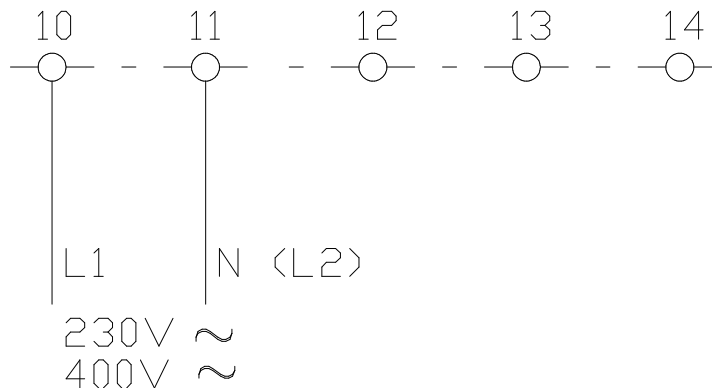
see CE advice, page 10

Short conductor length to be used between the input filter and the device

Operation with 60Hz: switch S3 contact 1 in position ON

Auxiliary voltage connection

Connection	terminal X5:10, X5:11
Power supply	230V~ or 400V~
Input current	0.1A
Phase position	regardless
Internal fuses	2.5Af



3 Electrical Installation

Direct power connection

Connection

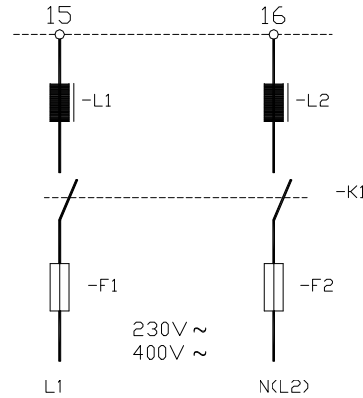
Phase L1 terminal X10:15
Phase L2 (N) terminal X10:16

Input fuses

Super fast acting fuses

Power choke

Inductance >200mH



Power connection with a transformer

Transformer performance

1.1 x continuous motor power

Secondary voltage

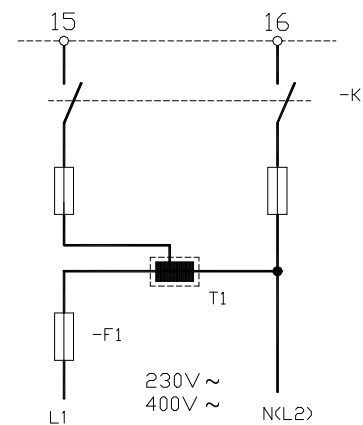
1.35 x motor power

Transformer fuses

Slow acting

Input fuses

Super fast acting fuses



Attention:

If the secondary voltages produced by the transformer are inferior to 60% of the rated device voltage, the voltage watchdog has to be adapted. These modifications may only be effected in the factory and thus, the transformer secondary voltage has to be indicated on order.

Internal watchdog for fuse failures



Motor connection

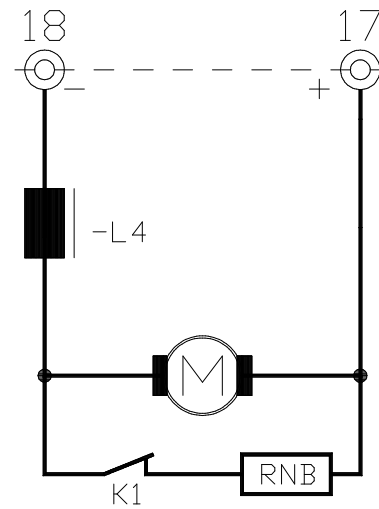
Connection

Motor - bolt X5:18
 Motor+ bolt X5:17

Armature choke

Inductance $-L4[mH = U/(I_A \times 2.4)$

an armature choke should always be used with a P1 devices



Warning:

Faulty switching will create arcing across the switch contacts.



Power supply failure - brake resistor

Break contact of the mains contactor K1
 in parallel to the motor armature
 without separation from the device

Attention:

Power lines have to be shielded and routed separately from control lines!
 For electro-magnetic interferences please refer to the CE advice.



3 Electrical Installation

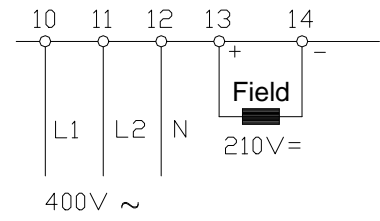
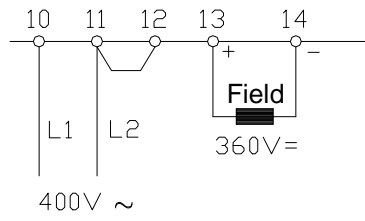
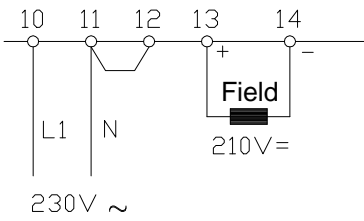
Field connection

Connection

Input
 Field negative
 Field positive

clamp
 X5:10, X5:11, X5:12
 X5:14
 X5:13

Field voltage



Power voltage

230V~
 400V~
 400V~ with N

Field voltage

200V=
 340V=
 200V=

Field current

fusing
 control

max. 1.5A
 2.5 Af
 dropped out

Tacho

Suitable actual value encoders:

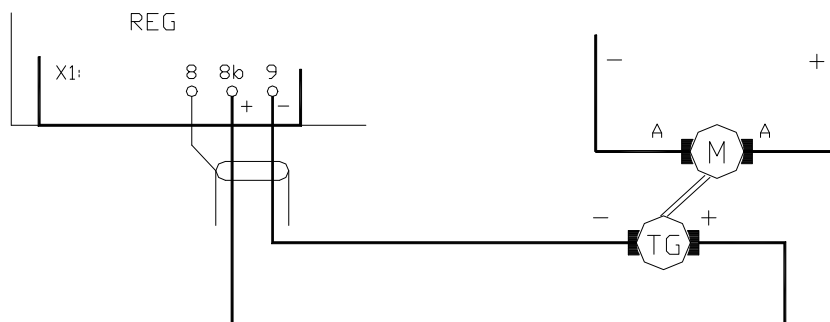
- DC tacho generator
- Brushless tacho generator with evaluation electronics
- Incremental encoders with evaluation electronics
- AC or three-phase tacho with rectification

Connection

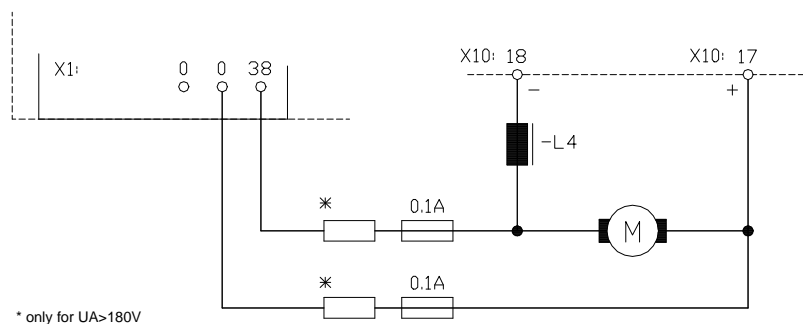
Control electronics (see Manual REG)

In case of a positive command value

Tacho positive	X 1:8b
Tacho negative	X 1:9
Shield	X 1:8



Armature voltage



* only for UA>180V

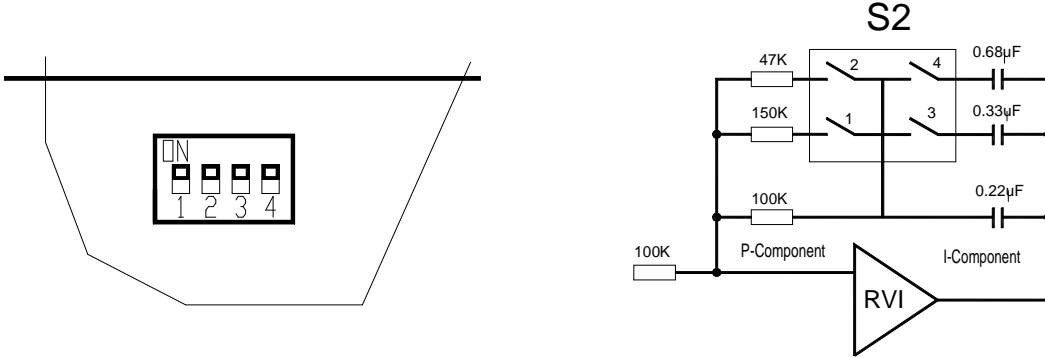
Ground referenced actual value

Fuses	2x 0.1A/500V	directly in the armature circuit
For armature voltage	>180V=	additional resistors are required
Use unit UNITEK EXZU-UA1		

4 Adjustment

Current controller - PI loop circuit

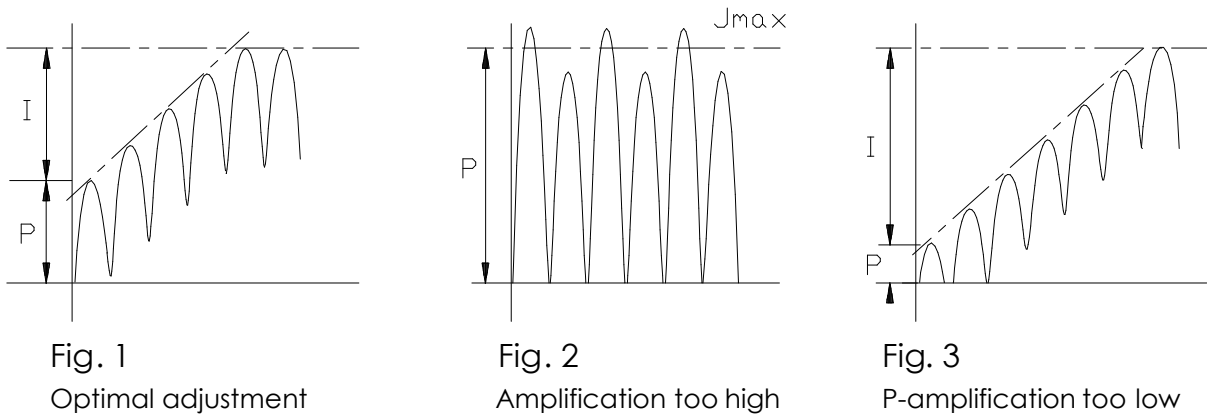
Adjustments with the DIP switch S2



Optimization of the current controller

- Connect an oscilloscope across the current actual value X3:21
- Current command value step-change 1V X3:16
- Increase the current command value by 1V steps to 10V
- Alter the P-amplification by means of the DIP switches S2:1 and S2:2
- Optimal adjustment see fig. 1
- Not permissible adjustment see fig. 2
- Alter the integral part by means of the DIP switches S2:3 and S2:4

Oscilloscope - Current adjustment



Displays

Some important functions are indicated by LEDs:

Display

	LED
Drive ready	BTB
Current controller enable	enable
Triggering enabled	enable triggering
Current command value direction	RVI-1

The green LEDs indicate the active states!

BTB signal - Drive ready

BTB signal	X3:25	>+10V
Error	X3:25	<+2V

Error

Auxiliary voltage supply	+24V, +15V, -15V
Power supply:	
Fuse failure	
Under-voltage	

In case of errors or failure the power section is internally disabled without delay.

Measurements

Measurement advice

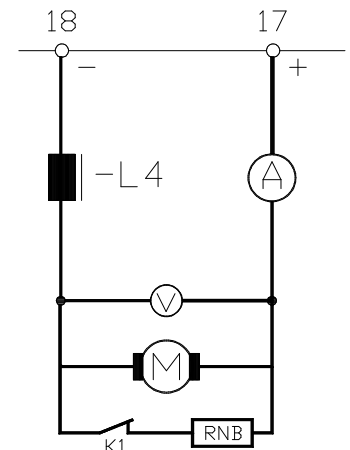
Measuring instruments: multimeters for current and voltage
 shunt or clamp-on ammeter

Measuring faults: mean value > actual value
 acc. to the form factor
 approx. 1 to 5%

Measured values

with a positive command value

Voltage:	X10:18 negative X10:17 positive
	max. 0.75 x power supply
Current:	ammeter in the motor circuit



Measured values across REG

Speed	X2:109	-5V (10V)	for ±100% speed
Current	X2:111	+5V (10V) f	or ±200% current
GND	X2:104		

5 Getting Started

1. Connection advice

Connect the drive in accordance with the P1 manual and the control electronics manual (e.g. REG).

Please observe in particular:

- Check the power supply voltage with that specified on the type plate.
- Insert the correct fuses according to the technical data (rf. to page 6)
- Check the field voltage connection and the motor and tacho connections!
- For 60Hz applications set the DIP switch S3, contact 1 to ON

2. Commissioning

Basic connections: Mains supply, field, tacho, or armature feedback, drive enable, command value.

For armature voltage control the tacho watchdog must be switched off.

2.1 Drive enable switch open or drive enable voltage 0V

Command value		0V
Switch S9		adjust to tacho voltage
for armature voltage control		adjust to 0
Switch S4		position 2
Switch S5		position 6
Potentiometer I _{max1}		left full scale
Potentiometer I _{max2}		adjust to approx. 10% of full scale
Potentiometer	XP	adjust to 50%
Potentiometer	ID	= 100%
Potentiometer	I _{xR}	= left full scale
Potentiometer	n _{max}	= left full scale
Potentiometer	INT	= left full scale

2.2 Apply the voltage

The LEDs L3 (BTB) and L7 (stationary) **must** light.
All other LEDs are off.

2.3 Close the switch 'drive enable' or apply a drive enable voltage of 10V

- The LEDs L1 and L2 must also light
- The drive must be at a standstill or turn slowly (offset, n_{min}).
- If the drive accelerates in the correct direction, the polarity of the tacho voltage and the armature voltage feedback must be changed.
- If the drive accelerates in the wrong direction, the polarity of the armature or the field must be changed.

2.4 Increase the command value voltage to approx. 10%

The drive must accelerate to approx. 10% of the speed.

If the rotation direction is wrong, change the polarity of the tacho and the field or the polarity of the tacho and the armature.

2.5 Current controller amplification

(Switch S2 on the power section)

The current amplification is adjusted to a low armature circuit inductance (all switches "On")

High inductance values can lead to motor oscillation which cannot be influenced by means of the speed controller. In this case, first set switch S2-2 to "Off".

If the drive still does not run smoothly, set the switch S2-1 to "Off".

The current response can be measured by means of an oscilloscope across the test point X4:20 (see page 17).

2.6 Speed controller amplification

Adjust on the REG board.

Adjust the P-term to the lowest possible setting from 1 to 5 (switch S4).

Adjust the I-term to match the axis momentum (switch S5):

large axis momentum - high adjusted value

small axis momentum - low adjusted value

With the command value set to 10% speed, increase the amplification by turning the potentiometer Xp clockwise. When the drive begins to oscillate, reduce the amplification by turning the potentiometer anti-clockwise by approximately 10%.

For the fine adjustment of the amplification the control response should be measured by means of an oscilloscope across the test point X4:15.

2.7 Further adjustments

such as speed, peak current, continuous current, etc. (rf. to the manual REG)

2.8 Switching Off

If the switch 'drive enable' is opened, or the drive enable voltage is switched to 0V, LED L1 and L2 will extinguish and the drive will be disabled.

DS1:K4 in position OFF!

After approx. 2s the thyristor triggering circuit is disabled.

2.9 Commissioning adjustments

The adjustments should be documented in the protocol and the adjustment potentiometers should be sealed with a suitable lacquer.

6 Guarantee

UNITEK products have a warranty against defects in material and workmanship for a period of one year from the date of shipment. All values from the pre- and final quality control checks are archived with the devices' serial numbers. UNITEK does not guarantee the suitability of the device for any specific application.

During the warranty period, UNITEK will, at its option, either repair or replace products that prove to be defective, this includes guaranteed functional attributes. UNITEK specifically disclaims the implied warranties or merchantability and fitness for a particular purpose. For warranty service or repair, this product must be returned to a service facility designated by UNITEK.

For products returned to UNITEK for warranty service, the Buyer shall prepay shipping charges to UNITEK and UNITEK shall pay shipping charges to return the product to the Buyer.

However, the Buyer shall pay all shipping charges, duties, and taxes for products returned to UNITEK from another country.

The foregoing warranty shall not apply to defects resulting from:

- * improper or inadequate repairs effected by the Buyer or a third party,
- * non-observance of the manual which is included in the all consignments,
- * non-observance of the electrical standards and regulations
- * improper maintenance
- * acts of nature

All further claims on transformation, diminution and replacement of any kind of damage, especially damage, which does not affect the UNITEK device, cannot be considered. Follow-on damage within the machine or system, which may arise due to malfunction or defect in the device cannot be claimed. This limitation does not affect the product liability laws as applied in the place of manufacture (i. e. Germany).

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The local legal regulations, and those of the Standards Authorities have to be adhered to. UNITEK does not assume any liability, expressly or inherently, for the information contained in this MANUAL, for the functioning of the device or its suitability for any specific application.

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The onus is on the reader to verify that the information here is current.

Customer: **Machine No.**

Device: **Series No.**

Control voltage [V~].....

Power voltage [V~].....

Field voltage [V=]

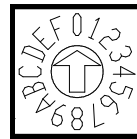
Inputs

Enable	Contact ?	Voltage [V=]
Nominal Value	Type	Voltage [V=]
Auxiliary nom. value	Type	Voltage [V=]
Current nom. value I_{max2}	external	Voltage [V=]

Speed controller settings

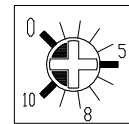
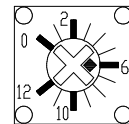
Switches

Tachometer adjustment	S9	Position
P - term	S4	Position
I - term	S5	Position
D- term	S8	Position



Potentiometers

Speed	n_{max}	P4	Position	...
Peak current	I_{max1}	P6	Position	...
Peak current	I_{max2}	P6	Position	...
Continuous current	I_D	P7	Position	...
Integrator	INT	P1	Position	...
Amplification	XP	P3	Position	...
IxR compensation	IxR	P2	Position	...



DIP - switches DS ..

ON Nr.

OFF Nr.

Setting-Current controller

Switch setting

Switch S2	open closed	(OFF) (ON)
Switch S3 contact 1	60 Hz 50 Hz	ON OFF

Measuring value

Armature voltage	max.	[V=]
Armature current	peak	[A=]
Armature current	steady	[A=]
Tachometer voltage	max.	[V=]
Acceleration	X4:16	V/ms]
Integrator	X4:14	[V/ms]

Motor data

Identification/name plate specifications

Producer

Type

Series number

Motor voltage [V=]

Motor current [A=]

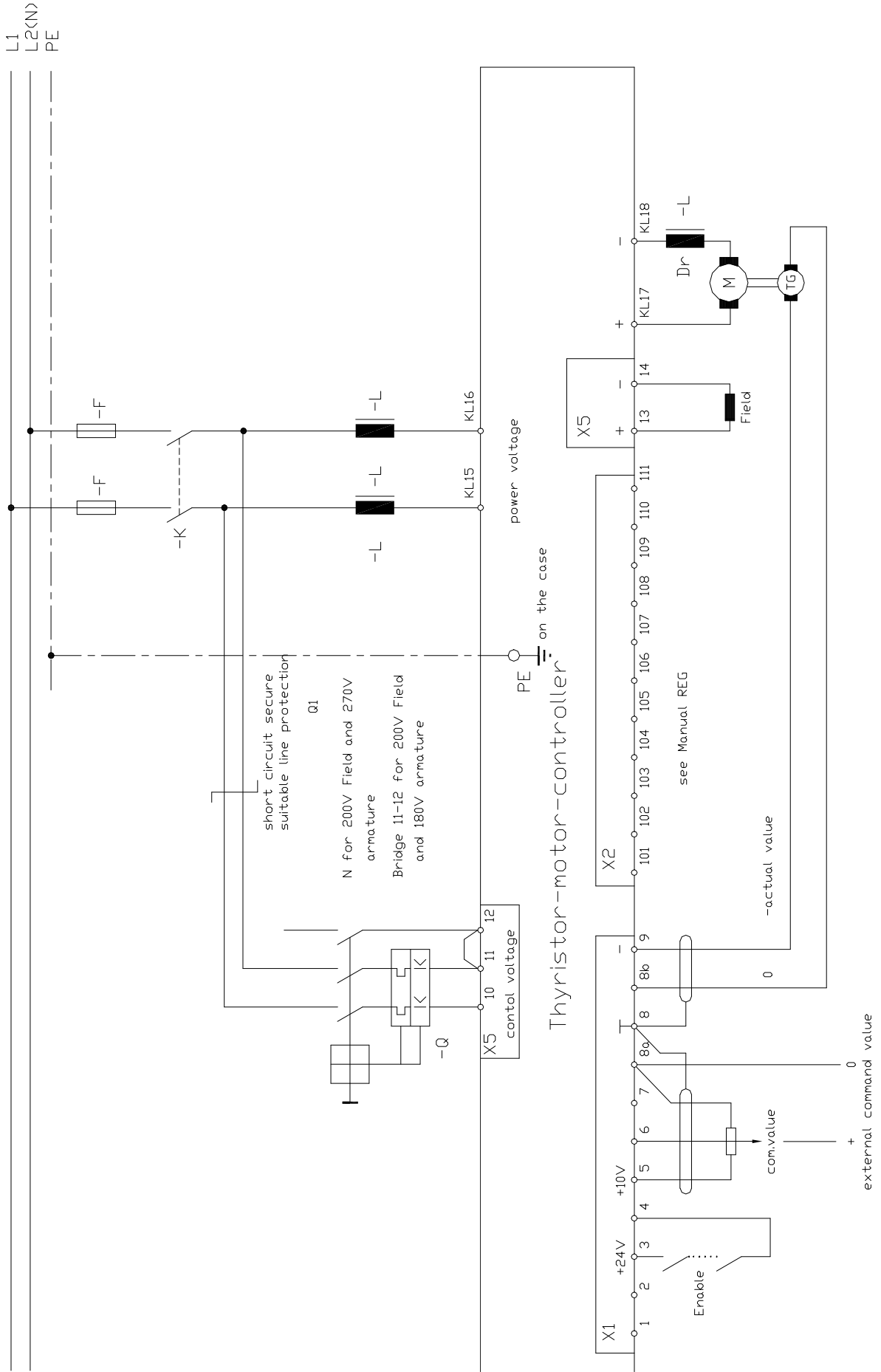
Tachometer voltage [V/min-1].

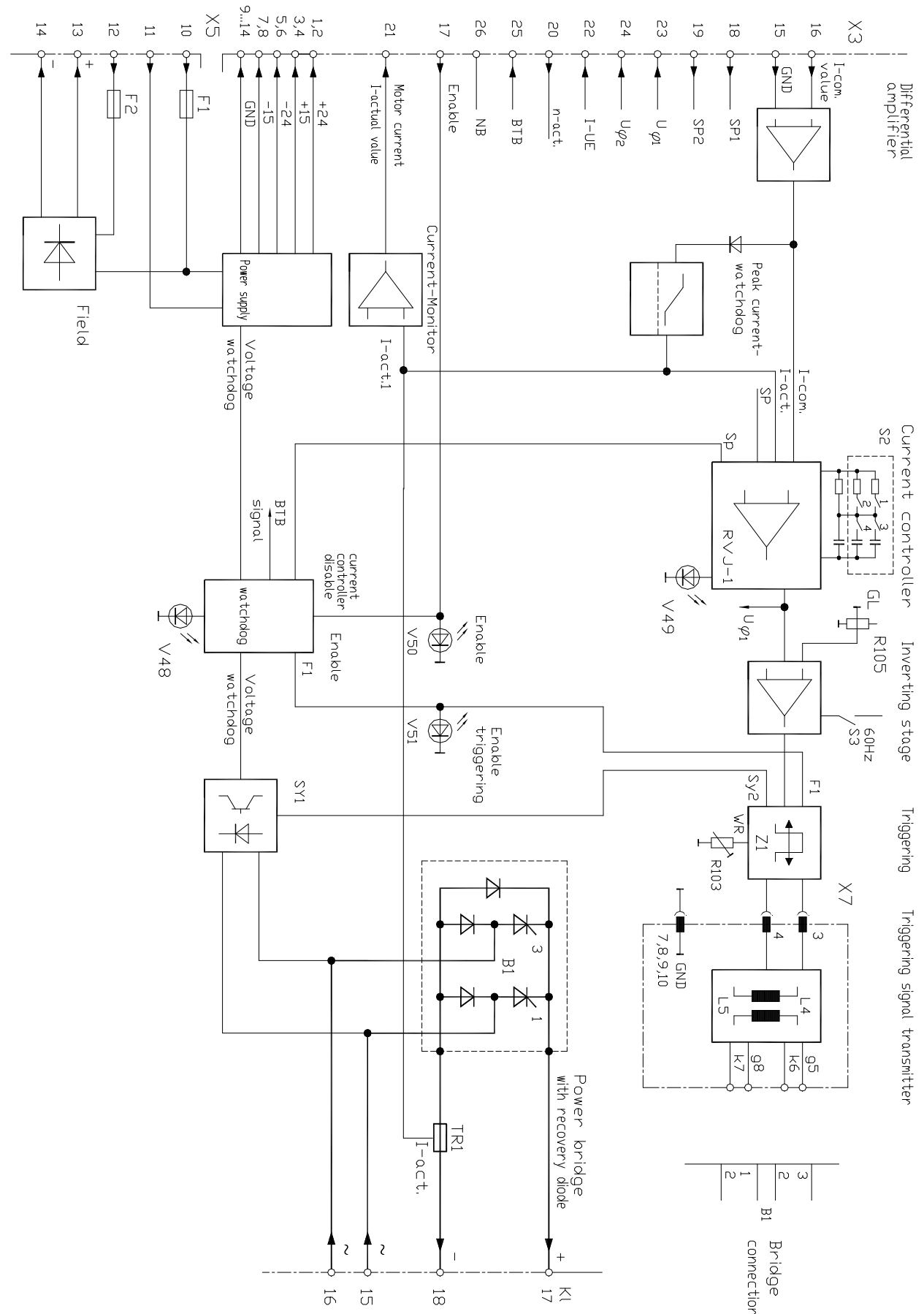
Tachometer type

Brake [V]

Fan [V].

Connection diagram





Circuit diagram P1- 15, 25A

